

# Uncertainty in AI driven physical simulation

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# Introduction

- Machine learning models are used to approximate interatomic potentials [1]

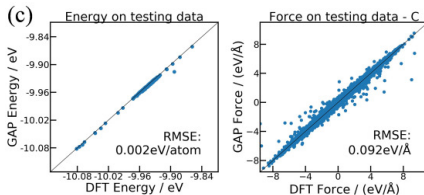


Figure 1: Energy and force predictions from NN approximation [3]

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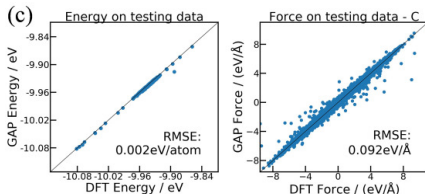
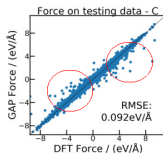


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- These models introduce epistemic uncertainty [5] to their predictions due to their training protocols.



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- How can the effect of the noise be mitigated? And how is uncertainty Quantification important for this task?

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## The $\phi^4$ model

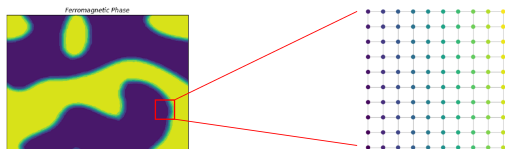


Figure 2: A  $\vec{\phi}$  configuration in the ferromagnetic phase (left) and a zoomed-in view of the lattice structure (right)

$$S[\vec{\phi}] = \sum_{x \in L} \left[ - \sum_{\kappa=1}^2 \beta \phi_x \phi_{x+e_{\kappa}} + \phi_x^2 + g (\phi_x^2 - 1)^2 \right]$$

- $-\sum_{\kappa=1}^2 \beta \phi_x \phi_{x+e_{\kappa}}$  interaction between neighbors.

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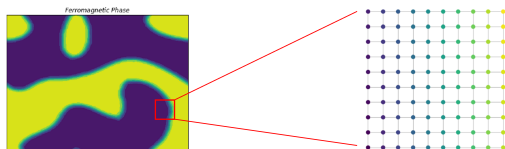


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- $-\sum_{\kappa=1}^2 \beta \phi_x \phi_{x+e_\kappa}$  interaction between neighbors.
- $\phi_x^2 + g (\phi_x^2 - 1)^2$  interaction term of the field.



# What are the consequences of the noise to the numerical simulations?

## Metropolis Hastings's (MH) Algorithm [4]

The MH algorithm is an MCMC method used to sample configurations for computing physical observables in high-dimensional spaces.

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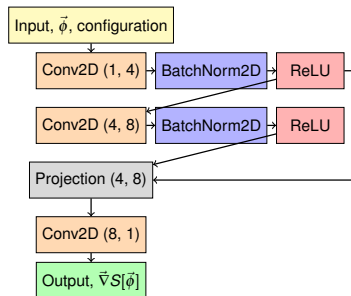
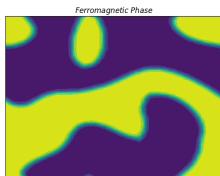
$$dS = S[\vec{\phi} + \delta\vec{\phi}] - S[\vec{\phi}] = \delta\vec{\phi} \cdot \nabla S[\vec{\phi}] + \text{extra terms} \quad (1)$$

- We accept the move if:

$$u \geq \min(1, \exp(-dS)), \text{ where } u \in [0, 1] \text{ is an uniform random number} \quad (2)$$

# What are the consequences of the noise to the numerical simulations?

## Residual Convolutional Neural Network (RCNN) approximation of the $\nabla S[\vec{\phi}]$



- **Training protocol:** 200 independent samples, 180 training, 20 test, with batch size 24, for 50 epochs, with **Mean Squared Error (MSE)** loss function.

# How does noise affect simulations?

## Predictions of the $\nabla S[\vec{\phi}]$ with the RCNN

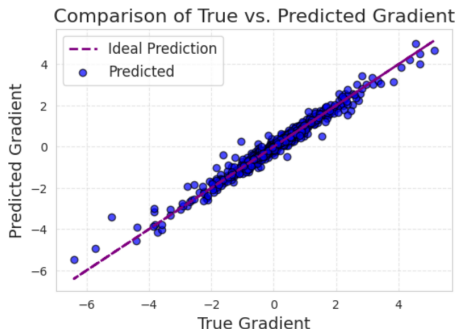


Figure 3: Predictions of the Gradient of the lattice field with good accuracy.

# How does noise affect simulations?

## Markov chain Trajectories

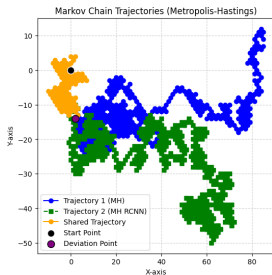


Figure 4: 2D Hypothetical Markov chain (MC) Trajectories

- Shared trajectory

$$\min(1, \exp(-\delta\vec{\phi} \cdot \nabla S[\vec{\phi}])) \simeq \min(1, \exp(-\delta\vec{\phi} \cdot \nabla S_{RCNN}[\vec{\phi}]))$$

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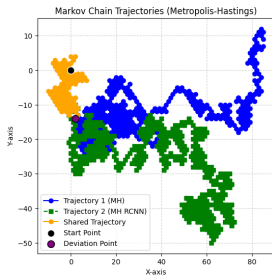


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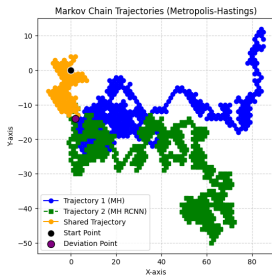


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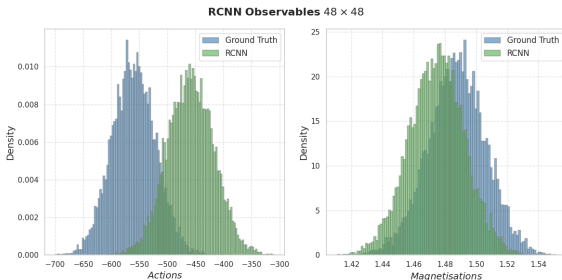
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- $\min(1, \exp(-\delta\vec{\phi} \cdot \nabla S_{RCNN}[\vec{\phi}]))$ , MH with RCNN
- $\min(1, \exp(-\delta\vec{\phi} \cdot \nabla S[\vec{\phi}]))$ , MH



# How does noise affect simulations?

## MH sampling configurations for observables with RCNN



**Figure 5:** Discrepancy of the computations of the observables, using the RCNN (green) and the Ground Truth (blue) algorithm.

# What is the nature of the noise?

We trained the RCNN model using the MSE loss function:

$$\mathcal{L}_{\text{MSE}} = \frac{1}{N} \sum_{i=1}^N \left\| \nabla S[\vec{\phi}]_i - \nabla \hat{S}[\vec{\phi}]_i \right\|_2^2 \quad (3)$$

MSE assumes that the residuals follow a Gaussian distribution because it corresponds to the maximum likelihood estimate under this assumption.

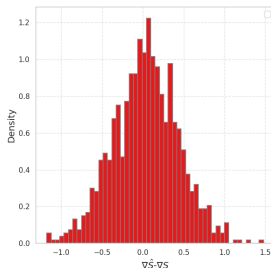


Figure 6: 1000 predictions for specific  $\vec{\phi}$  of one component of the  $\nabla S[\vec{\phi}]$

# How can the effect of the noise be mitigated?

## Penalty Technique [2]

The RCNN approximation can be written as a normal distribution around the true value.

$$\nabla \hat{S}_i - \nabla S_i = \varepsilon_i \sigma, \quad \varepsilon_i \sim \mathcal{N}(0, 1) \quad , \quad \forall i \in L \quad (4)$$

The introduced noise can be corrected with a **penalty factor** assuming that it follows a Gaussian distribution with variance  $\sigma^2$ . Thus, the new acceptance criteria is:

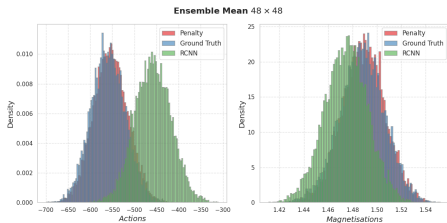
$$u \geq \min\left(1, e^{-\nabla \hat{S}_i \cdot \delta \vec{\phi} - \frac{\sigma^2 (\delta \phi)^2}{2}} \dots\right), \quad u \text{ is uniform random number } u \in [0, 1] \quad (5)$$

# How can the effect of the noise be mitigated?

## Ensemble technique plus penalty

We train  $N = 10$  machines to predict the  $\nabla S[\vec{\phi}]$  and we estimate the mean and the variance of the predictions with better precision trying to eliminate biases of the predictions.

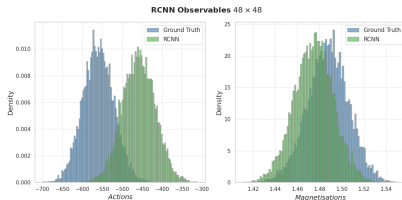
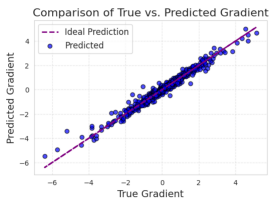
$$\nabla \hat{S}_{mean} = E[\nabla \hat{S}_N], \quad \sigma_{penalty}^2 = \mathbf{V}[\nabla \hat{S}_N], \quad \min(1, e^{-\nabla \hat{S}_{mean} \cdot \delta \vec{\phi} - \frac{\sigma_{penalty}^2 (\delta \phi)^2}{2}} - \dots)$$



**Figure 7:** Penalty plus ensemble method can mitigate the effect of the noise, enabling correct sampling.

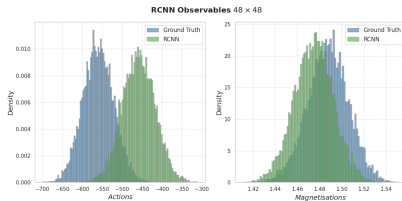
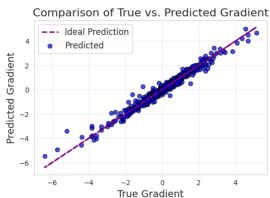
# Conclusions

- High-accuracy machine learning approximations influence the sampling process in the MH algorithm.

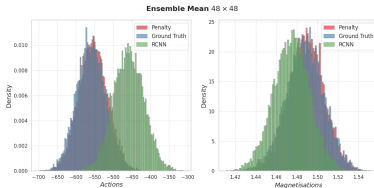


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- High-accuracy machine learning approximations influence the sampling process in the MH algorithm.



- We can mitigate the noise (Gaussian one) using a **penalty technique** and an ensemble method.



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- Write an article to publish our approach and results.



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- Write an article to publish our approach and results.
- Use more advanced techniques for uncertainty quantification (e.g. Bayesian neural networks.)

# References

- [1] Dylan M. Anstine and Olexandr Isayev. "Machine Learning Interatomic Potentials and Long-Range Physics". In: *The Journal of Physical Chemistry A* 127.11 (2023). PMID: 36802360, pp. 2417–2431. DOI: 10.1021/acs.jpca.2c06778. eprint: <https://doi.org/10.1021/acs.jpca.2c06778>. URL: <https://doi.org/10.1021/acs.jpca.2c06778>.
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Thank you for your attention.